## SYSMAC

# C200H-AD001/DA001 Analog I/O Units 

Operation Guide
Revised February 2001


## Notice:

OMRON products are manufactured for use according to proper procedures by a qualified operator and only for the purposes described in this manual.
The following conventions are used to indicate and classify precautions in this manual. Always heed the information provided with them. Failure to heed precautions can result in injury to people or damage to property.
! DANGER Indicates an imminently hazardous situation which, if not avoided, will result in death or serious injury.

WARNING
Indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury.

Indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury, or property damage.

## OMRON Product References

All OMRON products are capitalized in this manual. The word "Unit" is also capitalized when it refers to an OMRON product, regardless of whether or not it appears in the proper name of the product.
The abbreviation "Ch," which appears in some displays and on some OMRON products, often means "word" and is abbreviated "Wd" in documentation in this sense.

The abbreviation "PC" means Programmable Controller and is not used as an abbreviation for anything else.

## Visual Aids

The following headings appear in the left column of the manual to help you locate different types of information.

Note Indicates information of particular interest for efficient and convenient operation of the product.

Reference Indicates supplementary information on related topics that may be of interest to the user.

1, 2, 3... 1. Indicates lists of one sort or another, such as procedures, checklists, etc.

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## TABLE OF CONTENTS

PRECAUTIONS
1 Intended Audience
2 General Precautions
3 Safety Precautions
4 Operating Environment Precautions5 Application Precautions$\square$
$\square$
$\square$
$\square$
$\square$
$\square$
SECTION 1
System Design$\square$
$\square$
$\square$
$\square$
$\square$
SECTION 2C200H-AD001 Analog Input Unit$\square$
2-1 Before Operation ..... $\square$
2-2 Bit and DM Area Allocations$\square$
2-3 Functions and Programming$\square$
2-4 Troubleshooting$\square$
SECTION 3
C200H-DA001 Analog Output Units$\square$
3-1 Before Operation$\square$
3-2 Bit and DM Allocations ..... $\square$
3-3 Functions and Programming ..... $\square$
3-4 Troubleshooting$\square$
Appendices
A Standard Models ..... $\square$
B Specifications$\square$
C Data Memory Coding Sheets ..... $\square$
Index$\square$
Revision History

## About this Manual:

This guide describes the installation and operation of the C200H-AD001 Analog Input Unit and the C200H-DA001 Analog Output Unit and includes the sections described below.
The C200H-AD001 Analog Input Unit and the C200H-DA001 Analog Output Unit are analog-digital and digital-analog converters designed to work with the C 200 H or C 200 HS PC.
The $\mathrm{C} 200 \mathrm{H}-\mathrm{AD} 001$ can convert up to four analog inputs to digital (12-bit binary) form. The operator can select from three input ranges: 1 to 5 V and 4 to 20 mA (simultaneous use of voltage and current inputs possible), or 0 to 10 V (voltage inputs only). Useful functions, such as scaling, mean value, peak value, and square root, are built-in.
The C200H-DA001 can convert two digital (12-bit binary) signals to analog outputs. The operator can select from three output ranges: 1 to 5 V , 4 to 20 mA , or 0 to 10 V . Built-in functions include output limit, output limit alarm, and pulse output.
Please read this manual carefully and be sure you understand the information provided before attempting to install and operate the C200H-AD001 or the C200H-DA001

Section 1 describes the types of applications in which Analog I/O Units are used.
Section 2 describes the installation and operation of the C200H-AD001 Analog Input Unit, from installation and wiring through programming and operation.

Section 3 describes the installation and operation of the C200H-DA001 Analog Output Unit, from installation and wiring through programming and operation.

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## PRECAUTIONS

This section provides general precautions for using the Programmable Controller (PC) and Analog I/O Units.
The information contained in this section is important for the safe and reliable application of the Analog I/O Units. You must read this section and understand the information contained before attempting to set up or operate a PC system and Analog I/O Units.

1 Intended Audience
2 General Precautions
3 Safety Precautions
4 Operating Environment Precautions
5 Application Precautions

## 1 Intended Audience

This manual is intended for the following personnel, who must also have knowledge of electrical systems (an electrical engineer or the equivalent).

- Personnel in charge of installing FA systems
- Personnel in charge of designing FA systems
- Personnel in charge of managing FA systems and facilities


## 2 General Precautions

The user must operate the product according to the performance specifications described in the operation manuals.
Before using the product under conditions which are not described in the manual or applying the product to nuclear control systems, railroad systems, aviation systems, vehicles, combustion systems, medical equipment, amusement machines, safety equipment, and other systems, machines, and equipment that may have a serious influence on lives and property if used improperly, consult your OMRON representative.
Make sure that the ratings and performance characteristics of the product are sufficient for the systems, machines, and equipment, and be sure to provide the systems, machines, and equipment with double safety mechanisms.
This manual provides information for programming and operating OMRON Analog I/O Units. Be sure to read this manual before attempting to use the software and keep this manual close at hand for reference during operation.

1 WARNING It is extremely important that a PC and all PC Units be used for the specified purpose and under the specified conditions, especially in applications that can directly or indirectly affect human life. You must consult with your OMRON representative before applying a PC System to the above-mentioned applications.

## 3 Safety Precautions

WARNING Do not attempt to take any Unit apart while power is being supplied. Doing so may result in electric shock.

Do not touch any of the terminals or terminal blocks while power is being supplied. Doing so may result in electric shock.

## 4 Operating Environment Precautions

Caution Do not operate the control system in the following places:

- Locations subject to direct sunlight.
- Locations subject to temperatures or humidity outside the range specified in the specifications.
- Locations subject to condensation as the result of severe changes in temperature.
- Locations subject to corrosive or flammable gases.
- Locations subject to dust (especially iron dust) or salts.
- Locations subject to exposure to water, oil, or chemicals.
- Locations subject to shock or vibration.

Caution Take appropriate and sufficient countermeasures when installing systems in the following locations:

- Locations subject to static electricity or other forms of noise.
- Locations subject to strong electromagnetic fields.
- Locations subject to possible exposure to radioactivity.
- Locations close to power supplies.

Caution The operating environment of the PC System can have a large effect on the longevity and reliability of the system. Improper operating environments can lead to malfunction, failure, and other unforeseeable problems with the PC System. Be sure that the operating environment is within the specified conditions at installation and remains within the specified conditions during the life of the system.

## 5 Application Precautions

Observe the following precautions when using the PC.
$\lfloor$ WARNING Always heed these precautions. Failure to abide by the following precautions could lead to serious or possibly fatal injury.

- Always connect to a ground of $100 \Omega$ or less when installing the Units. Not connecting to a ground of $100 \Omega$ or less may result in electric shock.
- Always turn off the power supply to the PC before attempting any of the following. Not turning off the power supply may result in malfunction or electric shock.
- Mounting or dismounting I/O Units, CPU Units, Memory Cassettes, or any other Units.
- Assembling the Units.
- Setting DIP switch or rotary switches.
- Connecting or wiring the cables.
- Connecting or disconnecting the connectors.

Caution Failure to abide by the following precautions could lead to faulty operation of the PC or the system, or could damage the PC or PC Units. Always heed these precautions.

- Fail-safe measures must be taken by the customer to ensure safety in the event of incorrect, missing, or abnormal signals caused by broken signal lines, momentary power interruptions, or other causes.
- Interlock circuits, limit circuits, and similar safety measures in external circuits (i.e., not in the Programmable Controller) must be provided by the customer.
- Always use the power supply voltage specified in this manual. An incorrect voltage may result in malfunction or burning.
- Take appropriate measures to ensure that the specified power with the rated voltage and frequency is supplied. Be particularly careful in places where the power supply is unstable. An incorrect power supply may result in malfunction.
- Do not apply voltages to the Input Units in excess of the rated input voltage. Excess voltages may result in burning.
- Do not apply voltages or connect loads to the Output Units in excess of the maximum switching capacity. Excess voltage or loads may result in burning.
- Install external breakers and take other safety measures against short-circuiting in external wiring. Insufficient safety measures against short-circuiting may result in burning.
- Disconnect the functional ground terminal when performing withstand voltage tests. Not disconnecting the functional ground terminal may result in burning.
- Do not attempt to disassemble, repair, or modify any Units.
- Be sure that all the mounting screws, terminal screws, and cable connector screws are tightened to the torque specified in the relevant manuals. Incorrect tightening torque may result in malfunction.
- Leave the label attached to the Unit when wiring. Removing the label may result in malfunction if foreign matter such as wire cuttings enter the Unit.
- Remove the label after the completion of wiring to ensure proper heat dissipation. Leaving the label attached may result in malfunction.
- Use crimp terminals for wiring. Do not connect bare stranded wires directly to terminals. Connection of bare stranded wires may result in burning.
- Double-check all the wiring before turning on the power supply. Incorrect wiring may result in burning.
- Wire all connections correctly.
- Mount the Unit only after checking the terminal block completely.
- Be sure that the terminal blocks, Memory Units, expansion cables, and other items with locking devices are properly locked into place. Improper locking may result in malfunction.
- Check the user program for proper execution before actually running it on the Unit. Not checking the program may result in an unexpected operation.
- Confirm that no adverse effect will occur in the system before attempting any of the following. Not doing so may result in an unexpected operation.
- Changing the operating mode of the PC.
- Force-setting/force-resetting any bit in memory.
- Changing the present value of any word or any set value in memory.
- Resume operation only after transferring to the new CPU Unit the contents of the DM Area, HR Area, and other data required for resuming operation. Not doing so may result in an unexpected operation.
- Do not pull on the cables or bend the cables beyond their natural limit. Doing either of these may break the cables.
- Do not place objects on top of the cables or other wiring lines. Doing so may break the cables.
- Before touching the Unit, be sure to first touch a grounded metallic object in order to discharge any static built-up. Not doing so may result in malfunction or damage.
- Install the Units properly as specified in the operation manuals. Improper installation of the Units may result in malfunction.


## SECTION 1 System Design

This section describes the basic uses of Analog I/O Units in a Control System and illustrates the type of applications in which they might be found.

1-1 Introduction
1-2 Safety Precautions
1-3 Basic Configuration
1-4 Example Configurations
1-5 System Considerations

## 1-1 Introduction

The C200H-AD001 Analog Input Unit is used to convert the output of analog field devices, usually sensors, to a digital form (12-bit binary) that the PC can read. The C200H-DA001 Analog Output Unit converts the digital output of the PC to analog signals which drive analog field devices.


C200H-AD001
Analog Input Unit


C200H-DA001 Analog Output Unit

## 1-2 Safety Precautions

- Be sure that you have read this manual carefully and have understood the explanations before attempting any of the procedures described herein. OMRON accepts no responsibility for any damage or injury that may result from carrying out any operation that is not covered in this manual.
- Be sure to turn off the power supply to the PC before carrying out any of the following operations:
a) Mounting or removing a Unit.
b) Setting switches.
c) Mounting or removing a Terminal Block or connectors.
d) Wiring the System or Units.
- Use twisted-pair cables and keep high-voltage lines and power lines in separate ducts to reduce the risk of malfunctions due to electrical noise.
- Before turning on the power supply, check to be sure that the switch settings and wiring are correct.
- Check to be sure that the user program operates correctly.


## 1-3 Basic Configuration

This diagram shows some of the possible field devices for the Analog I/O Units. Any I/O device can be used as long as voltage/current requirements fall within the specified ranges.

The I/O device connected to the Analog I/O Unit will often serve as an interface for another device. For example, a preamplifier may amplify the output of a pressure gauge to the level required for the Analog Input Unit and a regulator may interface a heating system to control temperature.


## 1-4 Example Configurations

Below are two examples of how Analog I/O Units can be used in control systems. The first diagram shows a temperature regulating system and the second shows a servomotor positioning system.


## 1-5 System Considerations

## Number of Units

Slave Racks

C200HS/C200H/C200HX/HG/HE Analog I/O Units are classified as Special I/O Units. A maximum total of ten Special I/O Units (including PC Link Units) can be mounted to the CPU Rack, Expansion I/O Racks, and Slave Racks of a single PC. A single C200H-NC211 Position Control Unit counts as two Units.

The Units that belong to the various Special I/O Unit groups are shown in the following table. Their usage is limited according to the maximum current provided for the Rack and the amount of current consumed by each Unit. For details, refer to the C200HS/C200H Installation Guide.

Certain limitations apply to the number of Special I/O Units that can be mounted on Slave Racks. The following table shows the maximum number of Group A, B, C, and D Special I/O Units that can be mounted on a single Slave Rack when only Units of that group are used.

| A | B | C | D |
| :--- | :--- | :--- | :---: |
| High-speed Counters <br> Position Control Units <br> (NC111/112) | Multipoint I/O Units <br> Temperature Control Units <br> PID Control Units <br> Cam Positioner Units <br> Anall Units I/O Units <br> ID Sensor Units <br> Fuzzy Logic Units | Temperature Sensor Units <br> Voice Units | Position Control Units <br> (NC211) |
| 4 Units | - |  |  |
| - | 8 Units | - |  |
| - | - | - | - |
| - | - | 6 Units | - |

If Units from any of the four groups are to be combined, then both of the following two equations must be satisfied.

$$
\begin{aligned}
& 3 A+B+2 C+6 D \leqq 12 \\
& A+B+C+D \leqq 8
\end{aligned}
$$

Units can be mounted on other Racks as well, until the maximum total of ten Units has been reached. Remember, though, that a single C200H-NC2111 Position Control Unit counts as two Units. PC Link Units must also be counted among the total of ten Units.

## System Configuration Considerations

## Precautions

C200HS/C200H Special I/O Units are allocated IR area words according to the unit number switch settings on their front panels. They do not use the words of the slots in which they are mounted. For details regarding data area allocations, refer te $2-2$ ant $3-2$ IR and DM Bit Allocations.
With the $\mathbf{C 2 0 0 H}$, do not mount an Analog I/O Unit in the two slots adjacent to the CPU. Doing so would block peripheral devices such as the Programming Console from being connected.

Special I/O Units cannot be used on a C200H Remote I/O Slave Rack if the Slave Rack is connected to different model PC (i.e., C500, C1000H, or C2000H).

Be sure to turn off the power supply to the PC before installing or disconnecting Units or connecting lines.

To reduce the risk of malfunctioning due to electrical noise, wire input and output lines in separate ducts from high-voltage and power lines.
For further wiring precautions, refer to the respective sections on wiring for Analog Input Units and Analog Output Units.

## SECTION 2 <br> C200H-AD001 Analog Input Unit

This section provides the information required to install and operate a C200H-AD001 Analog Input Unit.
2-1 Before Operation
2-1-1 Nomenclature and Functions
2-1-2 Switch Settings
2-1-3 Wiring
2-2 Bit and DM Area Allocations
2-3 Functions and Programming
2-3-1 Input Signal Range Setting
2-3-2 Square Root
2-3-3 Scaling
2-3-4 Mean Value
2-3-5 Peak Value
2-3-6 Input Disconnection Detection
2-3-7 Data Setting Example and Programming Concepts
2-4 Troubleshooting$\square \square \square \square \square \square \square \square \square \square \square \square \square \square$

## 2-1 Before Operation

## 2-1-1 Nomenclature and Functions



Indicators

| Indicator | Color | Function |
| :--- | :--- | :--- |
| RUN | Green | Lit when the Analog Input Unit is operating correctly. If operation is not normal, this <br> indicator turns OFF and Unit operation is stopped. |
| BROKEN WIRE | Red | Lit when an input signal wire is disconnected. This indicator operates only when the <br> input range is set to 1 to $5 \mathrm{~V} / 4$ to 20 mA. |

## Functions

The following table briefly outlines the basic functions of the C200H-AD001. These functions are covered in more detail in-3 Functions and Programming.

| Function | Explanation |
| :--- | :--- |
| Input range setting | The input range can be set according to the input signal level that is to be used. The <br> same input range is used for all of the inputs for a particular Unit. The voltage range of <br> 1 to 5 V and the current range of 4 to 20 mA , however, can be used at the user's option <br> for any input. |
| Square root | Converts quadratic data, such as thermocouple input, to linear data. |
| Scaling | Converts an analog input signal to a preset range of BCD data for output. |
| Mean value | Sums the sampling data and calculates the mean value for output. |
| Peak value | Holds the maximum values for A/D conversion data, scaling data, mean data, and <br> square root data, and outputs them as output data. |
| Disconnection detection | The Disconnection Detection Flag is turned ON and the BROKEN WIRE indicator is lit if <br> the input signal wire becomes disconnected when 1 to $5 \mathrm{~V} / 4$ to 20 mA are set. |



## 2-1-2 Switch Settings

There are four settings necessary for this Unit: unit number, number of inputs, input range, and data reading mode.

## Unit Number

## Number of Inputs



The switch notch points to the unit number. The switch in the figure to the left is set to 0 . Odd numbers, in parentheses here, are not shown on the Unit.

Use a standard screwdriver and set a different unit number for each Analog I/O Unit. IR area memory is allocated according to unit number, as shown in the table below.

| Switch setting | Unit number | IR words | DM words |
| :---: | :---: | :---: | :---: |
| 0 | Unit \#0 | IR 100 to 109 | DM 1000 to 1099 |
| 1 | Unit \#1 | IR 110 to 119 | DM 1100 to 1199 |
| 2 | Unit \#2 | IR 120 to 129 | DM 1200 to 1299 |
| 3 | Unit \#3 | IR 130 to 139 | DM 1300 to 1399 |
| 4 | Unit \#4 | IR 140 to 149 | DM 1400 to 1499 |
| 5 | Unit \#5 | IR 150 to 159 | DM 1500 to 1599 |
| 6 | Unit \#6 | IR 160 to 169 | DM 1600 to 1699 |
| 7 | Unit \#7 | IR 170 to 179 | DM 1700 to 1799 |
| 8 | Unit \#8 | IR 180 to 189 | DM 1800 to 1899 |
| 9 | Unit \#9 | IR 190 to 199 | DM 1900 to 1999 |

Note 1. The unit number setting switch is factory set to 0 .
2. If two or more Special I/O Units are assigned the same unit number, an I/O UNIT OVER error will be generated and the PC will not operate.
3. Make the unit number settings with the power turned off to the PC. If the settings are made with the power on, they will not go into effect until either the power is turned off and then on again or the Special I/O Unit Restart Flag (AR0100 to AR0109) is turned ON.

There can be 1,2 , or 4 inputs depending on the settings of pins 1 and 2 , as shown in the table below.


The following table shows the effects of the various pin combinations. If there is no need to use all of the inputs, processing time can be shortened by setting the pins so that the smallest possible number of inputs is enabled.

| Pin number |  | Number of inputs | Inputs enabled |
| :---: | :---: | :---: | :--- |
| $\mathbf{1}$ | $\mathbf{2}$ |  |  |
| OFF | ON | 1 | Input 1 only is enabled. |
| ON | OFF | 2 | Inputs 1 and 2 only are enabled. |
| OFF | OFF | 4 | All inputs are enabled. |
| ON | ON | Not used. | - |

## Input Range

## Data Reading Mode

Use pin 3 to set the input range.

| Pin number 3 | Input range |  |
| :---: | :--- | :--- |
| OFF | Voltage input | 1 to 5 V |
|  | Current input | 4 to 20 mA |
| ON | Voltage input | 0 to 10 V |

Note The same input range is used for all of the inputs for a particular Unit. The voltage range of 1 to 5 V and the current range of 4 to 20 mA , however, can be used at the user's option at any input.

In normal mode, the input data is read only once before being converted from analog to digital. In filter mode, the input data is read three times and then the average values are converted from analog to digital. This helps to reduce the effects of electrical noise and so on. Using filter mode, however, results in longer processing time, as shown in the following table.

| Pin number 3 | Data reading mode | A/D conversion time |
| :---: | :--- | :--- |
| OFF | Normal mode | $2.5 \mathrm{~ms} / \mathrm{input}$ max. |
| ON | Filter mode | $4 \mathrm{~ms} / \mathrm{input}$ |

## 2-1-3 Wiring

Terminal Allocation
The following illustration shows the function of each terminal.

| Input 1 (-) | A0 | B0 | Voltage input 1 (+) |
| :---: | :---: | :---: | :---: |
|  |  | B1 | Current input 1 (+) |
| Not used. | A1 | B2 | Voltage input 2 (+) |
| Input 2 (-) | A2 | B3 | Current input 2 (+) |
| Not used. | A3 | B4 | Voltage input 3 (+) |
| Input 3 (-) | A4 | B5 | Current input 3 (+) |
| Not used. | A5 | B6 | Voltage input 4 (+) |
| Input 4 (-) | A6 | B7 | Current input 4 (+) |
| Not used. | A7 | B8 | Not used. |
| Common (Analog 0 V) | A8 | B9 | Common (Analog 0 V) |

The same input range is used for all of the inputs for a particular Unit. The voltage range of 1 to 5 V and the current range of 4 to +20 mA , however, can be used at the user's option at any input.
Use the DIP switch on the back panel of the Unit to set the input range and the number of inputs. (For details, refer tq-2-1-2 Switch Settings.)
When current input is used, short circuit the voltage input (+) and current input (+) terminals.
The common terminal is connected to the 0 V of the Analog Input Unit's analog circuit. Noise interference can be reduced by using shielded cables for input lines.
The A8 and B9 terminals are short circuited internally.

## Voltage Inputs

The following diagram illustrates the external wiring of voltage inputs for the C200H-AD001.


Note Terminals A8 and B9 are analog input ground terminals. They are not frame grounds and so do not connect them to a ground.

## Current Inputs

The following diagram illustrates the external wiring of current inputs for the C200H-AD001. When current inputs are used, use the short pins provided with the Unit to short circuit the $\mathrm{V}+$ and $\mathrm{I}+$ terminals as shown in the diagram.


Note Terminals A8 and B9 are analog input ground terminals. They are not frame grounds and so do not connect them to a ground.

## Input Wiring Considerations

When wiring inputs, apply the following points to avoid noise interference and optimize Analog Input Unit performance.

- Use shielded twisted-pair cable for external connections and power lines.
- Route input cables separately from the AC cable, and do not run the Unit's cables near a main circuit cable, high voltage cable, or a non-PC load cable.
- Be sure to install surge-absorbing diodes or surge absorbers for inductive loads (relays, solenoids, electromagnetic valves, etc.) They should be installed right next to relays and solenoids. Use surge-absorbing diodes with a dielectric strength of at least five times the circuit voltage.

DC Relay
AC Relay



- If there is noise interference from power lines (if, for example, the power supply is shared with electrical welding devices or electrical discharge machines, or if there is a high-frequency generation source nearby) install a noise filter at the power supply input area.
- Use at least a class-3 ground (to $100 \Omega$ or less), with as heavy a wire as possible (i.e., at least $1.25 \mathrm{~mm}^{2}$ ).


## 2-2 Bit and DM Area Allocations

## IR Area Allocation

C200H Analog Input Units are allocated ten words each from the portion of the IR area (IR 100 to IR 199) that is reserved for Special I/O Units. The words that are allocated a particular Analog Input Unit depend on the setting of the unit number on the front panel of the Unit. Those ten words are then reserved as an I/O refresh data area, and the bits that comprise that area are refreshed with every I/O refresh scan by the PC.


The OUT and IN refreshes are as seen from the PC.

Note The unit number that is set for an Analog Input Unit must not be used for any other Special I/O Unit. If the same unit number is set more than once, an I/O UNIT OVER error will be generated and operation will be stopped.

## DM Area Allocation

SYSMAC C200HS/C200H/C200HX/HG/HE PC

| (DM area) |  | Automatically transferred to each unit at power up or when Special I/O Restart Flag is turned ON. | (Fixed data area) |  |
| :---: | :---: | :---: | :---: | :---: |
| Unit \#0 | DM 1000 to 1011 |  | DM (m) | ling data |
| Unit \#1 | DM 1100 to 1111 |  | $\mathrm{DM}(\mathrm{~m}+7)$ | Scal |
| Unit \#2 | DM 1200 to 1211 |  | $\mathrm{DM}(\mathrm{~m}+8)$ | an |
| Unit \#3 | DM 1300 to 1311 |  | DM (m + 11) |  |
| Unit \#4 | DM 1400 to 1411 |  |  |  |
| Unit \#5 | DM 1500 to 1511 |  |  |  |
| Unit \#6 | DM 1600 to 1611 |  |  |  |
| Unit \#7 | DM 1700 to 1711 |  |  |  |
| Unit \#8 | DM 1800 to 1811 |  |  |  |
| Unit \#9 | DM 1900 to 1911 |  | $(\mathrm{m}=1000+100 \times$ unit number) |  |

(For more information regarding DM area allocation, refer to $D M$
Allocations at the end of this section.)

IR Allocations

| I/O | Wd <br> (IR) | Bit |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 15 | 14 | 13 | 12 | 11 | 10 | 09 | 08 | 07 | 06 | 05 | 04 | 03 | 02 | 01 | 00 |
| OUT | n | 0 | 0 | 0 | SQ | PK | Mean value processing |  |  |  | 0 | Scaling execution |  |  |  | OA | CP |
|  |  |  |  |  |  |  | Input 4 | Input 3 | Input 2 | Input 1 |  | Input 4 | Input 3 | Input 2 | Input 1 |  |  |
| IN | $\mathrm{n}+1$ | Input 1 A/D conversion data or processing data |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | $\mathrm{n}+2$ | Input 2 A/D conversion data or processing data |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | n+3 | Input 3 A/D conversion data or processing data |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | $\mathrm{n}+4$ | Input 4 A/D conversion data or processing data |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | $\mathrm{n}+5$ | 0 | 0 | 0 | 0 | 0 | 0 | 0 | OD | Input pts. 00: 4 pts. 01: 2 pts. 10: 1 pt. |  | IR | Disconnection detection |  |  |  | SE |
|  |  |  |  |  |  |  |  |  |  |  |  | Input 4 | Input 3 | Input 2 | Input 1 |  |  |
|  | $\begin{gathered} n+6 \\ \text { to } \\ n+9 \end{gathered}$ | Not used. |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |

Note The following abbreviations are used in this table. SQ: square root calculation; PK: peak value; OA: offset adjustment; CP: A/D conversion prohibited; OD: outputs disabled; IR: input range; SE: setting error.

## A/D Conversion Data

| Input range | Binary data |
| :---: | :---: |
| 0 to $10 \mathrm{~V}, 1$ to $5 \mathrm{~V}, 4$ to 20 mA | 0000 to 0FA0 |

Processing Data
When scaling, mean value processing, peak value, or square root calculation is executed, the resulting data is output.

Note When scaling is executed, it is set in words $n+1$ through $n+4$ in BCD.

## IR Area Contents: Outputs

| Address |  | Item | Contents |
| :---: | :---: | :---: | :---: |
| Word (IR) | Bit |  |  |
| n | 15 to 13 | - | Not used. Set each bit to 0 (i.e., OFF). |
|  | 12 | Square Root ON Bit | Turn this bit ON (i.e., set it to 1 ) to execute the square root calculation. It is used for all inputs. |
|  | 11 | Peak Value ON Bit | Turn this bit ON (i.e., set it to 1) to execute the peak value function. It is used for all inputs. |
|  | 10 to 07 | Mean Value ON Bit | Turn these bits ON (i.e., set them to 1 ) to calculate the mean values for the respective inputs. Bits 07 to 10 correspond to inputs 1 to 4. |
|  | 06 | - | Not used. Set to 0 (i.e., OFF). |
|  | 05 to 02 | Scaling ON Bit | Turn these bits ON (i.e., set them to 1) to execute scaling for the respective inputs. Bits 02 to 05 correspond to inputs 1 to 4 . |
|  | 01 | Offset adjustment | Turn this bit ON (i.e., set it to 1) to execute the offset adjustment. The adjustment is carried out automatically at power up, so this bit does not normally need to be used. |
|  | 00 | A/D conversion prohibition | Turn this bit ON (i.e., set it to 1 ) to prohibit A/D conversion. It is used for all inputs. |

IR Area Contents: Inputs

| Word (IR) | Bit | Item | Contents |
| :---: | :---: | :---: | :---: |
| $\mathrm{n}+1$ | 15 to 00 | Input 1 A/D conversion data or processing data | The A/D conversion data (binary) is set here for each input. (The data is set in BCD for scaling.) |
| $\mathrm{n}+2$ | 15 to 00 | Input 2 A/D conversion data or processing data |  |
| $\mathrm{n}+3$ | 15 to 00 | Input 3 A/D conversion data or processing data |  |
| $\mathrm{n}+4$ | 15 to 00 | Input 4 A/D conversion data or processing data |  |
|  | 15 to 09 | - | Not used. |
|  | 08 | Output disabled | Conversion data is unstable at power up, so this bit prohibits A/D conversion data from being output. It remains ON for approximately 100 ms after the power is turned on. |
|  | 07 to 06 | Number of inputs | The number of inputs ( 4,2 , or 1 ) is determined by the status of pin numbers 1 and 2 of the DIP switch on the rear panel of the Analog Input Unit. The status of pin 2 affects bit 07, and the status of pin 1 affects bit 06. |
| $\mathrm{n}+5$ | 05 | Input range | The status of this bit reflects the setting of pin 3 of the rear-panel DIP switch. |
|  | 04 to 01 | Input Disconnect Flag | When an input is disconnected, the corresponding bit is turned ON (i.e., is set to 1). Bits 01 to 04 correspond to inputs 1 to 4 respectively. (See note 1.) |
|  | 00 | Setting Error Flag | This bit turns ON (i.e., is set to 1 ) if the data set in the DM area is wrong. (See note 2.) |

Note 1. This bit turns ON under the following conditions:

- An input is 0.5 V or less when set for 1 to 5 V .
- An input is 2 mA or less when set for 4 to 20 mA .
- The input does not function when set for 0 to 10 V .

2. The Setting Error Flag turns ON when the scaling upper and lower limits are not in BCD or when the number of mean processing terms is 0000 or not in BCD.
3. Even if scaling or mean processing are not executed, and regardless of whether or not inputs are used, the data described in note 2 will cause the Setting Error Flag to turn ON. This will have no effect on operation, however.
4. $n=100+10 x$ unit number

DM Allocations

| Word | Bit |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 15 | 14 | 13 | 12 | 11 | 10 | 09 | 08 | 07 | 06 | 05 | 04 | 03 | 02 | 01 | 00 |
| DM (m) | Input 1, scaling lower limit data |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| DM (m+1) | Input 1, scaling upper limit data |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| DM (m+2) | Input 2, scaling lower limit data |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| DM (m+3) | Input 2, scaling upper limit data |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| DM ( $m+4$ ) | Input 3, scaling lower limit data |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| DM ( $m+5$ ) | Input 3, scaling upper limit data |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| DM ( $m+6$ ) | Input 4, scaling lower limit data |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| DM (m+7) | Input 4, scaling upper limit data |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| DM ( $m+8$ ) | Input 1, number of samples for mean processing |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| DM ( $m+9$ ) | Input 2, number of samples for mean processing |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| DM (m+10) | Input 3, number of samples for mean processing |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| DM (m+11) | Input 4, number of samples for mean processing |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |

Note 1. The DM area that is used is a read-only area, so the data cannot be written from the program. Use the Programming Console to set data by changing the present value or changing three words together.
2. The range for setting scaling data is 0000 to 9999 (BCD). Make sure that the lower limit is smaller than the upper limit.
3. The range for setting the number of times that sampling is to be executed for mean value processing is 0002 to 9999 (BCD).
4. Data that is set in the DM area is transferred either at the time of power up or when the Special I/O Unit Restart Bit is turned ON. Any data that is set in the meantime will remain invalid until then.

## DM Contents

| Words | Bits | Item | Data contents |
| :--- | :--- | :--- | :--- |
| DM $(\mathrm{m})$ to $\mathrm{DM}(\mathrm{m}+7)$ | 15 to 00 | Scaling data | The scaling data (upper and lower limits) is set in <br> BCD (0000 to 9999), using two words for each <br> input. Set the lower limit in the rightmost word and <br> the upper limit in the leftmost word, and make sure <br> that the lower limit is smaller than the upper limit. |
| DM $(\mathrm{m}+8)$ to DM $(\mathrm{m}+11)$ | 15 to 00 | Number of terms for <br> calculating mean value | The number of samples to be taken for calculating <br> the mean value is set in BCD (0002 to 9999) for <br> each input. DM words $m+8$ through $m+11$ <br> correspond to inputs 1 to 4. |

## 2-3 Functions and Programming

The C200H-AD001 Analog Input Unit provides six functions:

- Input signal range setting
- Square root
- Scaling
- Mean value
- Peak value
- Input disconnection detection

These functions are set using Unit switches and Peripheral Devices, such as a Programming Console. The words allocated to the Unit in the DM Area (DM m to DM $m+11$ ) cannot be written from user program and all data set in these words must be written from a Peripheral Device.
When inputting data from a Programming Console, use the operations to change present values. When inputting from the SSS (SYSMAC Support Software), use the DM editing operations.
The data set in the DM area is transferred to the Analog Input Unit when either of the following steps is taken. Be sure to perform one or the other of these steps whenever new data has been set or data has been changed.

- Turning ON the power to the C200H/C200HS/C200HX/HG/HE CPU.
- Turning ON the Restart Bit allocated to the Unit as a Special I/O Unit (AR 0100 to 0109).
Any or all of the six functions can be used at the same time. Data will be processed in the following sequence and the final results will be output to words $n+1$ to $\mathrm{n}+4$ : analog-to-digital conversion $\rightarrow$ square root $\rightarrow$ scaling $\rightarrow$ mean value $\rightarrow$ peak value.


## 2-3-1 Input Signal Range Setting

The C200H-AD001 can convert analog input signals in three ranges:
0 to 10 V , 1 to 5 V , or 4 to 20 mA . The range is set on pin 3 of the DIP switch as shown below

| Pin 3 | Input range |
| :--- | :--- |
| OFF | 1 to 5 V |
|  | 4 to 20 mA |
| ON | 0 to 10 V |

If the 0 to 10 V setting is used, it must be used for all four inputs. The 1 to 5 V and 4 to 20 mA ranges can be used at the same time for different inputs.

The digital data is in 12-bit binary code ( 0000 to 0FAO), and resolution is $1 / 4000$ full scale.

## Analog Input vs. Digital Output



Note An offset error is likely to occur when power is turned on. The full scale of converted data is 4000, and the remaining 95 is used for offset/gain.

## 2-3-2 Square Root

The square root function is used to convert quadratic data, such as thermocouple inputs, to linear data. The function is activated for all inputs when the Square Root ON Bit (IR 1n012, where n is the unit number) is turned ON.
The square root function can be used at the same time as the scaling and mean value functions. If all three functions are used, the square root of the converted input value is taken first and then scaling and mean value calculations are performed.

The square root function uses an 80-bit floating decimal system. Only the integer value is kept, the remainder is truncated.

Square root value $=\sqrt{(\text { converted input value }(B C D) \times 4000)}$
Note If the Square Root ON Bit (IR 1 n 012 , where n is the unit number) is turned ON , square root calculations will be performed for all inputs.

## 2-3-3 Scaling

The scaling function automatically converts the analog input signal to a preset range for use in specific engineering applications. The scaling function is executed for an input when its Scaling Bit is ON, i.e., it can be set separately for each input. This function can be used at the same time as other functions.
To set this function for an input, turn ON the Scaling Bit corresponding to that input in word n .


The high and low limits of the output data range for each input are 4-digit BCD values preset in the DM area, as shown in the following table ( n is the unit number set on the front panel.) A lower limit must be less than the corresponding upper limit.

| DM word | Range limit <br> (BCD) | DM word | Range limit <br> (BCD) | Bit of IR <br> 1n0 | Scaling bit |
| :---: | :---: | :---: | :---: | :---: | :--- |
| 1 n00 | Input 1 lower limit | $1 n 04$ | Input 3 lower limit | 02 | Input 1 |
| $1 n 01$ | Input 1 upper limit | $1 n 05$ | Input 3 upper limit | 03 | Input 2 |
| $1 n 02$ | Input 2 lower limit | $1 n 06$ | Input 4 lower limit | 04 | Input 3 |
| $1 n 03$ | Input 2 upper limit | $1 n 07$ | Input 4 upper limit | 05 | Input 4 |

Set the scaling data with the Programming Console, this data cannot be changed from the user's program.
Data set in the DM area is transmitted when the Unit is turned on or initialized. If data is modified in the middle of a session, then the modified data becomes effective the next time the Unit is turned on, or by toggling the appropriate Special I/O Restart Bit in the AR area.
Scaled data is calculated using the formula below. Only the integer value is kept, the remainder is truncated.

Scaling data $=\frac{\text { Input data } \times \text { (upper limit }- \text { lower limit) }}{4000}+$ lower limit

## Example

## Resolution

Note 1. Scaling will not be performed and unscaled (normal) data will be output if the
contents of DM words allocated to the Unit is not BCD or if a lower limit is
Note 1. Scaling will not be performed and unscaled (normal) data will be output if the
contents of DM words allocated to the Unit is not BCD or if a lower limit is greater than the corresponding upper limit.
2. The Setting Error Flag (bit 00 in IR 1 n 5 , where n is the unit number) will be
turned ON if the contents of DM m to $\mathrm{DM} \mathrm{m}+7$ is not BCD.
3. The Setting Error Flag will turn ON whenever DM area data is not BCD regardless of whether an input is being used and regardless of whether or not scaling is set. Operation, however, will be normal in these cases.
If a $5-\mathrm{V}$ input is received, it would be converted to $2000(5 / 10 \times 4000)$ and then scaled as shown below.

Scaling data $=\frac{2000 \times(9000-1000)}{4000}+1000=5000$

If the difference between an upper limit and the corresponding lower limit (upper limit - lower limit) is 4000 or greater, the resolution is fixed at $1 / 4000$. If the differences is less than 4000, the resolution will be reduced proportionately.
For example, if the upper limit minus the lower limit is 2000, the resolution is 1/2000.

## 2-3-4 Mean Value

The mean value function sums a specified number of terms of converted input data and divides by the number of terms preset the DM area.
If the Mean ON Bit for an input is ON (bits 07 to 10 of word n ), the mean value will be output to the corresponding word in the PC. The desired number of terms must be set in the corresponding word in the DM area between DM m+8 and $D M m+11$. The setting can be between 0002 and 9999 (BCD).


The mean value functions can be used in combination with any of the other functions.
Set the mean data for each input with the Programming Console. This data cannot be changed from the user's program. Set the mean data for all 4 inputs even when using only one input. If there is a mistake in the data for even 1 input, the Setting Error Flag will be activated, though operation will continue.
The mean value is calculated using the formula below. When the Mean Enable Bit turns ON, the converted data will read " 0000 " until the mean value is calculated for the first time.

Mean value $=\frac{\text { Sum of converted input values }}{\text { Number of terms (mean data) }}$
The maximum mean function conversion time $=2.5 \mathrm{~ms} \times$ the sum of the number of terms for all inputs

Note 1. Mean value calculation will not be performed and normal data will be output if the number of terms set in the DM area is 0000 or is not BCD.
2. The Setting Error Flag (bit 00 in IR 1 n 5 , where n is the unit number) will be turned ON if the number of terms set in the DM area is 0000 or is not BCD.
3. The Setting Error Flag will turn ON whenever the number of terms set in the DM area is 0000 or is not BCD regardless of whether an input is being used and regardless of whether or not scaling is set. Operation, however, will be normal in these cases.

## 2-3-5 Peak Value

The peak value function holds the maximum output value for every input. This function can be used at the same time an any or all of the other functions.
The output value that will be held is one of the following depending on what other functions are set: converted input value, scaled value, mean value, and square root. Data will be processed in the following sequence and the maximum value of the final results will be output to words $n+1$ to $n+4$ : analog-to-digital conversion $\rightarrow$ square root $\rightarrow$ scaling $\rightarrow$ mean value $\rightarrow$ peak value.
The peak value function is activated for all 4 inputs when the Peak Value ON Bit (IR 1n011, where n is the unit number) is turned ON and reset when it is turned OFF.

Note If the Peak Value ON Bit (IR 1n011, where n is the unit number) is turned ON, the peak value will be held for all inputs.

## Mean and Peak Values

Data will be output as illustrated below when both the mean value and the peak value functions are used. In this example, mean value \#2 will be output as the first peak value even if mean value \#1 is larger because the Peak Value ON Bit was turned ON after mean value \#1 was output.


## 2-3-6 Input Disconnection Detection

The Input Disconnect Flags will be turned ON when an the input signal level is less than $0.5 \mathrm{~V} / 2 \mathrm{~mA}$ and the input signal range is set at 1 to $5 \mathrm{~V} / 4$ to 20 mA . These flags will not turn ON when the input signal range is set at 0 to 10 V . The Input Disconnect Flags are contained in in word IR $\mathrm{n}+5$, as shown below.


The BROKEN WIRE indicator on the Analog Input Unit will light whenever any of the Input Disconnect Flags turn ON.

Note 1. The Input Disconnect Flags will operate only when the Conversion Inhibit Bit (bit 00 of $I R n$ ) is OFF.
2. Input disconnection is detected for all input set on pins 1 and 2 of the backpanel DIP switch. If an input that is not being used (i.e., not connected) is specified on the DIP switch, the Input Disconnect Flag will turn ON.
3. The current peak value will be held even if a disconnected input is detected.

## 2-3-7 Data Setting Example and Programming Concepts

## Data Settings

## Basic Settings

The following settings are used in this example. Data in the DM area is set using the SSS, a Programming Console, or another Peripheral Device.

Turn power to the PC off then then back on or turn ON the Special I/O Unit Restart Bit allocated to the Unit (AR 0100 to AR 0109) after setting the data so that the data is read into the Analog Input Unit.

| Item | Setting |
| :--- | :--- |
| Unit number | 0 (allocated words: IR 100 to IR 109 and DM 1000 to DM 1011) |
| Inputs used | Inputs 1 to 4 |

## Details

| Item |  | Input 4 | Input 3 | Input 2 | Input 1 |
| :--- | :--- | :--- | :--- | :--- | :--- |
| Input signal range |  | 1 to 5 V | 4 to 20 mA | 1 to 5 V | 1 to 5 V |
| Scaling | Lower limit | - | 0400 | 1000 | 1000 |
|  | Upper limit | - | 1000 | 5000 | 5000 |
| Number of terms for <br> mean value calculation | - | 50 | - | 10 |  |

## DM Area Data

| DM word | Contents | Data |
| :---: | :---: | :--- |
| DM 1000 | 1000 | Input 1 lower limit for scaling |
| DM 1001 | 5000 | Input 1 upper limit for scaling |
| DM 1002 | 1000 | Input 2 lower limit for scaling |
| DM 1003 | 5000 | Input 2 upper limit for scaling |
| DM 1004 | 0400 | Input 3 lower limit for scaling |
| DM 1005 | 1000 | Input 3 upper limit for scaling |
| DM 1006 | 0000 | Input 4 lower limit for scaling |
| DM 1007 | 0000 | Input 4 upper limit for scaling |
| DM 1008 | 0010 | Input 1 number of terms for mean value |
| DM 1009 | 0000 | Input 2 number of terms for mean value |
| DM 1010 | 0050 | Input 3 number of terms for mean value |
| DM 1011 | 0000 | Input 4 number of terms for mean value |

## Programming

## Reading Output Data

The types of programming required to use an Analog Input Unit are described in this section. Refer to the operation manual for the C200H/C200HS/C200HX/ $\mathrm{HG} / \mathrm{HE}$ for details on programming.

The converted input value (or the results of calculations performed on it) can be read from the output words IR $n+1$ to IR $n+4$, and moved to other words in memory using MOV(21) and/or XFER(70). MOV(21) is used to move one word at a time and $\operatorname{XFER}(70)$ is used to move more than one word at a time.


Moves the output data from IR 101 (input 1) to DM 0001.


Moves the output data from IR 101 to IR 104 (inputs 1 to 4) to DM 0001 to DM 0004.

## Scaling

Set 4-digit BCD values for the lower and upper limits for scaling in DM $m$ to $\mathrm{DM} \mathrm{m}+7$. These words cannot be written from the program and must be written using a Peripheral Device, such as a Programming Console.

For example, use the following procedure to set scaling between 1000 and 5000 for input 1.
1, 2, 3... 1. Set the lower and upper limits in DM 1000 and DM 1001.

| DM word | Contents | Data |
| :---: | :---: | :--- |
| DM 1000 | 1000 | Input 1 lower limit for scaling |
| DM 1001 | 5000 | Input 1 upper limit for scaling |

2. Turn ON IR 10002 (Scaling ON Bit for input 1). Scaling will begin for input 1 as soon as this bit is turned ON. This bit can be changed from the program using the following type of programming.


## Mean Value

## Peak Value

## Square Root

Set the 4-digit BCD value for the number of terms for mean value calculation in $\mathrm{DM} \mathrm{m}+8$ to $\mathrm{DM} \mathrm{m}+11$. The number of terms can be between 2 and 9999 . These words cannot be written from the program and must be written using a Peripheral Device, such as a Programming Console.
For example, use the following procedure to set mean value calculation for every 10 inputs for input 1.
1, 2, 3... 1. Set the number of terms (10) in DM 1008.

| DM word | Contents | Data |
| :---: | :---: | :--- |
| DM 1008 | 0010 | Number of terms for mean value calcula- <br> tion for input 1 |

2. Turn ON IR 10007 (Mean Value ON Bit for input 1). Mean value calculations will begin for input 1 as soon as this bit is turned ON. This bit can be changed from the program using the following type of programming.


The peak value function can be used to hold the maximum output value for all outputs by turn ON the Peak Value ON Bit (IR10011). The peak value will be held individually for all inputs when this bit is turned ON. This bit can be changed from the program using the following type of programming.


The square root function can be used to convert quadratic data to linear data by turn ON the Square Root ON Bit (IR10012). The square root will be calculated individually for all inputs when this bit is turned ON. This bit can be changed from the program using the following type of programming.


## 2-4 Troubleshooting

Detection When Errors Occur

When an error occurs, the contents are output to the SR and HR areas. The following tables show the various errors that may occur, along with their probable causes and remedies.

| Unit error | Probable causes and operations | Possible remedies |
| :--- | :--- | :--- |
| Disconnection error | - Causes of error <br> - Input signal wire is disconnected. <br> - Input signal range is set to "1 to 5 V " but input is 0.5 <br> V or less. <br> - Input signal range is set to "4 to 20 mA " but input is <br> 2 mA or less. <br> - Disconnect indications <br> - BROKEN WIRE indicator is lit. <br> - The Input Disconnect Flag (IR n+5, bits 01 to 04) <br> that corresponds to the erroneous input signal is <br> turned ON (except when the input range is 0 to <br> 10 V). | Check the input signal wires, terminal <br> block, and input voltage. |
| Setting error | The data set in the DM area is wrong. In this case, <br> the Setting Error Flag (IR n+5, bit 00) will be ON. | Check the contents of the data. |
| Output disabled | The converted data is unstable, as, for example, <br> when the power is first turned on. In this case, the <br> Output Disabled Flag (IR n+5, bit 08) will be ON. | - |
| RUN indicator not lit | The RUN indicator on the Unit is not lit even though <br> power is turned on to the PC, and none of the errors <br> described in this table are applicable. | Replace the Unit. |


| CPU error | Probable causes and operations | Possible remedies |
| :--- | :--- | :--- |
| CPU waiting | - The Special I/O Unit is defective. <br> - The PC will not run. | - Replace the Special I/O Unit. <br> - The defective Unit should appear as \$ <br> signs only in the I/O table read opera- <br> tion. |
| Duplicated unit number | One number is assigned to more than one Special <br> I/O Unit. In this case the PC will not run and <br> SR25415 will turn ON. | Do not assign the same number to more <br> than one Unit. Use the I/O table read <br> operation to display unit numbers. |
| Special I/O Unit error | An error has occurred in the refresh signal between <br> the CPU and the Special I/O Unit. In this case, only <br> the Special I/O Unit stops. SR 25415 is turned ON. | Check AR 0000 to AR 0009 for the unit <br> number of the Unit in error. After <br> correcting the error, set restart (OFF <br> (OON OOFF) in AR 0100 to AR 0109. If <br> the error does not clear after <br> initialization, replace the Unit. |

## Special I/O Unit Error Detection Bit (SR)

| Bit | Error | Explanation | Operation status |
| :---: | :--- | :--- | :--- |
| SR 25415 | Duplicated unit number | The same number is assigned to <br> more than one Special I/O Unit. | PC operation stops. |
|  | Special I/O Unit error | An error has occurred in the refresh <br> signal between the CPU and the <br> Special I/O Unit | Operation stops only for the faulty <br> Unit. |

Special I/O Unit Error Flags (AR)

| Bit | Item | Function |
| :---: | :---: | :---: |
| AR 0000 | Unit \#0 Error Flag | When one of the CPU errors described above occurs, the AR bit turns ON for the Unit where the error occurred. |
| AR 0001 | Unit \#1 Error Flag |  |
| AR 0002 | Unit \#2 Error Flag |  |
| AR 0003 | Unit \#3 Error Flag |  |
| AR 0004 | Unit \#4 Error Flag |  |
| AR 0005 | Unit \#5 Error Flag |  |
| AR 0006 | Unit \#6 Error Flag |  |
| AR 0007 | Unit \#7 Error Flag |  |
| AR 0008 | Unit \#8 Error Flag |  |
| AR 0009 | Unit \#9 Error Flag |  |

## Special I/O Unit Restart Bits (AR)

Turn ON the Special I/O Unit Restart Bits in the following circumstances:

- After DM data has been set or replaced.
- To restart Unit operation after clearing an error.

The same effect can be achieved by turning off the power to the PC and then turning it on again.

| Bit | Item | Function |
| :---: | :---: | :---: |
| AR 0100 | Unit \#0 Restart Bit | Special I/O Units can be restarted by turning the |
| AR 0101 | Unit \#1 Restart Bit | corresponding bits ON. |
| AR 0102 | Unit \#2 Restart Bit |  |
| AR 0103 | Unit \#3 Restart Bit |  |
| AR 0104 | Unit \#4 Restart Bit |  |
| AR 0105 | Unit \#5 Restart Bit |  |
| AR 0106 | Unit \#6 Restart Bit |  |
| AR 0107 | Unit \#7 Restart Bit |  |
| AR 0108 | Unit \#8 Restart Bit |  |
| AR 0109 | Unit \#9 Restart Bit |  |

This section provides the information required to install and operate a C200H-DA001 Analog Output Unit.
3-1 Before Operation
3-1-1 Nomenclature and Functions
3-1-2 Switch Settings
3-1-3 Wiring
3-2 Bit and DM Allocations
3-3 Functions and Programming$\square$
3-3-1 Output Signal Range Setting
3-3-2 Output Limits
3-3-3 Output Limit Alarms
3-3-4 Pulse Output
3-3-5 Data Setting Example and Programming Concepts
3-4 Troubleshooting$\square$$\square$
$\square$
$\square$

## 3-1 Before Operation

## 3-1-1 Nomenclature and Functions



Indicators

| Indicator | Color | Function |
| :--- | :--- | :--- |
| RUN | Green | Lit when the Analog Output Unit is operating correctly. If operation is not normal, this <br> indicator turns OFF and Unit operation is stopped. |
| ALARM | Red | Lit when an alarm is output as a result of the upper or lower limits being exceeded, |

Functions The following table briefly outlines the basic functions of the C200H-DA001. These functions are covered in more detail ing-3 Functions and Programming.

| Function | Explanation |
| :--- | :--- |
| Output range setting | The output range can be set according to the output signal level that is to be used. The <br> same output range is used for all of the outputs for a particular Unit. The voltage range <br> of 1 to 5 V and the current range of 4 to 20 mA , however, can be used at the user's <br> option at any output. |
| Output limit | The output limit function sets upper and lower limits on the output signal. The upper and <br> lower limits are preset in the DM area. The output remains at the limit level as long as <br> the output limit function is activated. |
| Output limit alarm | This function activates an alarm if the output signal is outside of the range defined by <br> the upper and lower limits preset in the DM area, but it does not alter the output level. It <br> is possible to include a deadband, which delays the resetting of the alarm. The output <br> limit alarm turns ON and OFF according to the following conditions. |
| Pulse output | This function creates a 0 V to 5 V pulse output separate from the analog output. |

The following diagram shows the basic internal configuration of the Analog Output Unit.


## 3-1-2 Switch Settings

There are four settings necessary for this Unit: unit number, output range, pulse output line, and pulse output ON/OFF.

## Unit Number

DIP Switch Settings

The switch notch points to the unit number. The switch in the figure to the left is set to 0 . Odd numbers, in parentheses here, are not shown on the Unit.

Use a standard screwdriver to set a different unit number for each Analog I/O Unit. IR area memory is allocated according to unit number, as shown in the table below.

| Switch number | Unit number | IR words | DM words |
| :---: | :---: | :---: | :---: |
| 0 | Unit \#0 | IR 100 to 109 | DM 1000 to 1099 |
| 1 | Unit \#1 | IR 110 to 119 | DM 1100 t 1199 |
| 2 | Unit \#2 | IR 120 to 129 | DM 1200 to 1299 |
| 3 | Unit \#3 | IR 130 to 139 | DM 1300 to 1399 |
| 4 | Unit \#4 | IR 140 to 149 | DM 1400 to 1499 |
| 5 | Unit \#5 | IR 150 to 159 | DM 1500 to 1599 |
| 6 | Unit \#6 | IR 160 to 169 | DM 1600 to 1699 |
| 7 | Unit \#7 | IR 170 to 179 | DM 1700 to 1799 |
| 8 | Unit \#8 | IR 180 to 189 | DM 1800 to 1899 |
| 9 | Unit \#9 | IR 190 to 199 | DM 1900 to 1999 |

Note 1. The unit number setting switch is factory set to 0 .
2. If two or more Special I/O Units are assigned the same unit number, an I/O UNIT OVER error will be generated and the PC will not operate.
3. Make the unit number settings with the power turned off to the PC. If the settings are made with the power on, they will not go into effect until either the power is turned off and then on again or the Special I/O Unit Restart Flag (AR0100 to AR0109) is turned ON.

Set pins 1 through 3 before powering up the system. Pin 4 is not used, so please leave it set to OFF.


## Output Range

Use pin 1 to set the output range.

| Pin number 3 | Output range |  |
| :---: | :--- | :--- |
| OFF | Voltage input | 1 to 5 V |
|  | Current input | 4 to 20 mA |
| ON | Voltage input | 0 to 10 V |

Note The same output range is used for all of the outputs for a particular Unit. The voltage range of 1 to 5 V and the current range of 4 to 20 mA , however, can be used at the user's option at any output.

## Pulse Output Line

Pulse Output ON/OFF

Use pin 2 to set the pulse output line.
Pin 2 OFF: Output 1
Pin 2 ON: Output 2
Use pin 3 to set pulse outputs to ON or OFF.
Pin 3 OFF: Pulse output OFF
Pin 3 ON: Pulse output ON

## 3-1-3 Wiring

Terminal Allocation
The following illustration shows the function of each output.

|  | B0 | Voltage output $1(+)$ |  |
| :--- | :--- | :--- | :--- |
| Voltage output $1(-)$ | A0 | B1 | Current output $1(+)$ |
| Current output $1(-)$ | A1 | B2 | Pulse output $1(+)$ |
| Pulse output $1(-)$ | A2 | B3 | Voltage output $2(+)$ |
| Voltage output $2(-)$ | A3 | B4 | Current output $2(+)$ |
| Current output $2(-)$ | A4 | B5 | Pulse output $2(+)$ |
| Pulse output $2(-)$ | A5 | B6 | Not used. |
| Not used. | A6 | B7 | Upper limit alarm output 1 |
| Lower limit alarm output 1 | A7 | B8 | Upper limit alarm output 2 |
| Lower limit alarm output 2 | A8 | B9 | Alarm output common |

The Analog Output Unit has two built-in output lines, but it is not possible to simultaneously use one of them for both voltage and current outputs.
The same output range is used for all of the outputs for a particular Unit. The voltage range of 1 to 5 V and the current range of 4 to 20 mA , however, can be used at the user's option at any output.
Pulse output is possible for either output 1 or output 2, but not for both. Refer to -1-2 Switch Settings for details.

## Output Wiring

The following diagram shows the external wiring of outputs for the C200H-DA001.


Note 1. The maximum current capacity for this alarm output (open-collector output) is $100 \mathrm{~mA} /$ circuit.
2. A single output line cannot be used for voltage and current output at the same time.

## Output Wiring Considerations

When wiring outputs, apply the following points to avoid noise interference and optimize Analog Output Unit performance.

- Use shielded twisted-pair cable for external connections and power lines.
- Route output cables separately from the AC cable, and do not run the Unit's cables near a main circuit cable, high voltage cable, or a non-PC load cable.
- Be sure to install surge-absorbing diodes or surge absorbers for inductive loads (relays, solenoids, electromagnetic valves, etc.) They should be installed right next to relays and solenoids. Use surge-absorbing diodes with a dielectric strength of at least five times the circuit voltage.

- If there is noise interference from power lines (if, for example, the power supply is shared with electrical welding devices or electrical discharge machines, or if there is a high-frequency generation source nearby) install a noise filter at the power supply output area.
- Use at least a class-3 ground (to $100 \Omega$ or less), with as heavy a wire as possible (i.e., at least $1.25 \mathrm{~mm}^{2}$ ).

When using the C200H-DA001 Analog Output Unit, a voltage (current) may be output momentarily from the output terminal when the power supply to the PC is turned ON or OFF.
Approximately 10 V will be output for approximately 1 second after the power is turned ON or OFF.
If this causes a problem, provide countermeasures so that the power supply or output timing of external devices differs from the ON/OFF timing of the power supply to the PC.

## 3-2 Bit and DM Allocations

## IR Allocations

C200H/C200HS Analog Output Units are allocated ten words each from the portion of the IR area (IR 100 to IR 199) that is reserved for Special I/O Units. The words that are allocated a particular Analog Output Unit depend on the setting of the unit number setting switch on the front panel of the Unit. Those ten words are then reserved as an I/O refresh data area, and the bits that comprise that area are refreshed with every I/O refresh scan by the PC.


The OUT and IN refreshes are as seen from the PC.

Note The unit number that is set for an Analog Input Unit must not be used for any other Special I/O Unit. If overlapping numbers are set, an I/O UNIT OVER error will be generated and operation will be stopped.

## DM Allocations


(For more information regarding DM address allocation, refer to the DM Address Allocation Chart at the end of this section.)

IR Allocations


Note The following abbreviations are used in this table. OP: output prohibited; O2L: output 2 limit; O1L: output 1 limit; UL: upper limit; LL: lower limit; SE: setting error.
IR Area Contents (Outputs)

| Address |  | Item | Contents |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Word (IR) | Bit |  |  |  |  |  |  |  |  |
| n | 15 to 00 | Output 1 setting data | Sets output 1 data in binary. This becomes duty ratio data when pulse outputs are set. The range is 0000 to 0 FFF. |  |  |  |  |  |  |
| $\mathrm{n}+1$ | 15 to 00 | Output 2 setting data | Sets output 2 data in binary. This becomes duty ratio data when pulse outputs are set. The range is 0000 to 0FFF. |  |  |  |  |  |  |
| n+2 | 15 to 09 | - | Not used. Set all bits to "0." |  |  |  |  |  |  |
|  | 08 | Output prohibited | Turn ON to prohibit outputs. This bit is used for outputs 1 and 2. |  |  |  |  |  |  |
|  | 07 | Output 2 limit | Turn ON to execute output 2 limit. |  |  |  |  |  |  |
|  | 06 | Output 1 limit | Turn ON to execute output 1 limit. |  |  |  |  |  |  |
|  | 05 | Output 2 alarm | Turn ON to execute output 2 alarm. |  |  |  |  |  |  |
|  | 04 | Output 1 alarm | Turn ON to execute output 1 alarm. |  |  |  |  |  |  |
|  | 03 | - | Not used. Turn OFF (i.e., set to "0"). |  |  |  |  |  |  |
|  | 02 to 00 | Pulse cycle | Sets the pulse period. |  |  |  |  |  |  |
|  |  |  | $\begin{array}{l\|l} \hline \text { Pulse period } & 1 \\ \hline \end{array}$ |  |  | 2 s | 5 s | 10 s | 20 s |
|  |  |  | Bit | 02 | 0 | 0 | 0 | 0 | 1 |
|  |  |  |  | 01 | 0 | 0 | 1 | 1 | 0 |
|  |  |  |  | 00 | 0 | 1 | 0 | 1 | 0 |

IR Area Contents (Inputs)

| Word (IR) | Bit | Item | Contents |
| :---: | :---: | :---: | :---: |
| $\mathrm{n}+3$ | 15 to 09 | - | Not used. |
|  | 08 | Output 2 limit detected | Upper limit: Turns ON when output 2 value is greater than the upper limit. |
|  | 07 |  | Lower limit: Turns ON when output 2 value is less than the lower limit. |
|  | 06 | Output 1 limit detected | Upper limit: Turns ON when output 1 value is greater than the upper limit. |
|  | 05 |  | Lower limit: Turns ON when output 1 value is less than the lower limit. |
|  | 04 | Output 2 alarm (See note.) | Upper limit: Turns ON when output 2 value is greater than the alarm upper limit. |
|  | 03 |  | Lower limit: Turns ON when output 2 value is less than the alarm lower limit. |
|  | 02 | Output 1 alarm (See note.) | Upper limit: Turns ON when output 1 value is greater than the alarm upper limit. |
|  | 01 |  | Lower limit: Turns ON when output 1 value is less than the alarm lower limit. |
|  | 00 | Setting error | This bit turns ON if the data set in the DM area is wrong. (See note 2.) |

Note When alarm flags turn ON, their status can be read from external connection terminals A7, A8, B7, and B8. (Refer to $3^{-1-3}$ Wiring.) At that time the ALARM indicator on the display panel of the Unit will light.

## DM Allocations

| Word | Bit |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 15 | 14 | 13 | 12 | 11 | 10 | 09 | 08 | 07 | 06 | 05 | 04 | 03 | 02 | 01 | 00 |
| DM m | Output lower limit (0000 to 0FFF) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| DM (m+1) | Output upper limit (0000 to OFFF) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| DM (m+2) | Alarm lower limit (0000 to 0FFF) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| DM (m+3) | Alarm upper limit (0000 to 0FFF) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| DM (m+4) | Alarm dead band (0000 to 0FFF) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |

Note 1. The DM area that is used is a read-only area, so the data cannot be written from the program. Use the Programming Console to set data by changing the present value or changing three words together.
2. Data that is set in the DM area is transferred either at the time of power up or when the Special I/O Unit Restart Bit is turned ON. Any data that is set in the meantime will remain invalid until then.
3. The values set in DM are used for both output lines (i.e., for output 1 and output 2).
4. $m=1000+100 \times$ unit number.

## 3-3 Functions and Programming

The C200H-DA001 Analog Output Unit provides 4 functions

- Output signal range setting
- Output limit
- Output limit alarm
- Pulse output

These functions are set using Unit switches and Peripheral Devices, such as a Programming Console. The words allocated to the Unit in the DM Area (DM m to DM $m+4$ ) cannot be written from user program and all data set in these words must be written from a Peripheral Device.
When inputting data from a Programming Console, use the operations to change present values. When inputting from the SSS (SYSMAC Support Software), use the DM editing operations.
The data set in the DM area is transferred to the Analog Output Unit when either of the following steps is taken. Be sure to perform one or the other of these steps whenever new data has been set or data has been changed.

- Turning ON the power to the $\mathrm{C} 200 \mathrm{H} / \mathrm{C} 200 \mathrm{HS}$ CPU.
- Turning ON the Restart Bit allocated to the Unit as a Special I/O Unit (AR 0100 to 0109).


## 3-3-1 Output Signal Range Setting

The C 200 H -DA001 converts 12 -bit binary data (3-digit hexadecimal) from the PC to analog output in one of three ranges: 0 to 10 V , 1 to 5 V , or 4 to 20 mA .

The C200H-DA001 can convert analog output signals in three ranges: 0 to 10 V , 1 to 5 V , or 4 to 20 mA . The range is set on pin 1 of the DIP switch as shown below.

| Pin $\mathbf{1}$ | Input range |
| :--- | :--- |
| OFF | 1 to 5 V |
|  | 4 to 20 mA |
|  | 0 to 10 V |

If the 0 to 10 V setting is used, it must be used for all two outputs. The 1 to 5 V and 4 to 20 mA ranges can be used at the same time for different outputs.

## Digital Output vs. Analog Input



0 V to 10 V Output (pin 1 ON)


1 V to 5 V and 4 mA to 20 mA Outputs (pin 1 OFF)

## 3-3-2 Output Limits

The output limit function can be used to establish upper and lower limits for the output signal. The limits can be used to restrict the output for any of a number of possible reasons, e.g., to prevent unsuitable outputs from occurring even when incorrect data is set.
This function can be used at the same time as the output limit alarm function.
The upper and lower limits are preset as binary values in the DM area (lower limit in $\mathrm{DM} m$ and upper limit in $\mathrm{DM} m+1$ ). The output will remain between the upper and lower limits as long as the output limit function is activated.

If the output goes beyond either limit, an Output Limit Flag (bits 05 to 08 in IR $\mathrm{n}+3$ ) will turn ON and the output will remain at the limit value


Use the following procedure to set upper and lower limits.
1, 2, 3... 1. Set the lower and upper limits in DM m and $\mathrm{DM} \mathrm{m}+1$. The setting range is between 0000 and OFFF (binary data). Set the limits from the Programming Console. This data cannot be changed from the user's program.
Note Calculations of the desired limit can be made as shown in the following example. To set an upper limit of 8 V for a 0 to 10 V range setting, use the following equation and set the results ( $0 C C C$ ) in $\mathrm{DM} \mathrm{m}+1$ : $8 / 10 \times 0 F F F=0 C C C$
2. Turn power to the PC off then then back on or turn ON the Special I/O Unit Restart Bit allocated to the Unit (AR 0100 to AR 0109).
3. Turn ON the Output Limit ON Bit for the desired output:

Output 1 Limit ON Bit: Bit 06 of IR $\mathrm{n}+2$
Output 2 Limit ON Bit: Bit 07 of IR $\mathrm{n}+2$

## 3-3-3 Output Limit Alarms

This function activates an alarm if the output signal is outside of the range defined by the upper and lower limits preset in the DM area, but it does not alter the output level. It is possible to include a deadband, which delays the resetting of the alarm.


This function can be used at the same time as the output limit function.
The output limit alarms turn ON and OFF according to the following conditions.
Upper limit:
ON: analog output $\geq$ output limit alarm upper limit
OFF: analog output < output limit alarm upper limit - deadband width
Lower limit:
ON: analog output $\leq$ output limit alarm lower limit
OFF: analog output > output limit alarm lower limit + deadband width
When any of the Output Limit Alarm Flags turn ON, the ALARM indicator on the Unit will light and signals will be generated on external terminals A7, A8, B7, and B8 (refer to - $\mathbf{- 1}^{-1-3}$ Wiring for details).
Use the following procedure to set upper and lower limit alarms.
1, 2, 3... 1. Set the lower and upper alarm limits in $D M m+2$ to $D M m+4$. The setting range is between 0000 and OFFF (binary data). Set the limits from the Programming Console. This data cannot be changed from the user's program.

Note Calculations of the desired limit can be made as shown in the following example. To set an upper limit alarm at 4.75 V for a 1 to 5 V range setting, use the following equation and set the results (OFOO) in DM $m+1:(4.75-1) /(5-1) \times 0 F F F=15 / 16 \times 0 F F F=0 F 00$
2. Turn power to the PC off then then back on or turn ON the Special I/O Unit Restart Bit allocated to the Unit (AR 0100 to AR 0109).
3. Turn ON the Output Alarm ON Bit for the desired output:

Output 1 Alarm ON Bit: Bit 04 of IR $n+2$
Output 2 Alarm ON Bit: Bit 05 of IR n+2

## 3-3-4 Pulse Output

The pulse output function can be used to create a 0 to 5 V pulse output for either output 1 or 2 in addition to the analog output.
The pulse period and duty ratio (ON/OFF ratio) can be set for the pulse output. These settings can be made from the user program.


Note The resolution of the duty ratio is $1 / 256$.
Use the following procedure to set a pulse output.
1, 2, 3... 1. Turn ON pin 3 of the DIP switch on the back of the Unit to select pulse output.
2. Turn OFF pin 2 to select output 1 , or ON to select output 2 . Both outputs cannot be pulse at the same time.
3. Set the pulse period in bits 00 to 02 of $\operatorname{RR} \mathrm{n}+2$ as shown below.

| Bis in IR n |  |  | Period |
| :--- | :--- | :--- | :--- |
| $\mathbf{0 0}$ | $\mathbf{0 1}$ | $\mathbf{0 2}$ |  |
| 0 | 0 | 0 | 1 s |
| 1 | 0 | 0 | 2 s |
| 0 | 1 | 0 | 5 s |
| 1 | 1 | 0 | 10 s |
| 0 | 0 | 1 | 20 s |

4. Set the duty ratio (ON/OFF ratio) for the pulse output in IR n. Refer tq $3-3-5$ Data Setting Example and Programming Concepts for setting methods.

## Calculating Settings

To set a duty ratio of $80 \%$, set the results of the following calculation (OCCC) in IR n : 80/100 $\times 0$ FFF $=0$ CCC.

If either the duty ratio or period is changed during operation, the output will not change until 1 full period has been completed.


## 3-3-5 Data Setting Example and Programming Concepts

## Data Settings

The following settings are used in this example. Data in the DM area is set using the SSS, a Programming Console, or another Peripheral Device. Turn power to the PC off then then back on or turn ON the Special I/O Unit Restart Bit allocated to the Unit (AR 0100 to AR 0109) after setting the data so that the data is read into the Analog Output Unit.

| Item | Setting |
| :---: | :--- |
| Unit number | 0 (allocated words: IR 100 to IR 109 and DM 1000 to DM 1004) |


| Item | Output 1 | Output 2 |
| :--- | :--- | :--- |
| DM word for storing output data | DM 0000 | DM 0001 |
| Lower limit output bit | IR 00100 | - |
| Upper limit output bit | IR 00101 | - |
| Lower limit alarm output terminal | - | A8 |
| Upper limit alarm output terminal | - | B8 |

## Details

| Item | Output 1 | Output 2 |
| :--- | :--- | :--- |
| Output signal range | 1 to 5 V | 4 to 20 mA |
| Output limit function | ON | OFF |
| Limit alarm function | OFF | ON |


| Item |  | Actual value | Setting |
| :--- | :--- | :--- | :--- |
| Output limits | Lower limit | 1.25 V | 0100 |
|  | Upper limit | 4.75 V | 0 F 00 |
|  | Lower limit | 6 mA | 0200 |
|  | Upper limit | 19 mA | 0 F 00 |
|  | Deadband | 0.5 mA | 0080 |

## DM Area Settings

| DM word | Data | Setting |
| :--- | :--- | :--- |
| DM 1000 | 0100 | Output limit lower limit |
| DM 1001 | 0 F00 | Output limit upper limit |
| DM 1002 | 0200 | Alarm lower limit |
| DM 1003 | 0F00 | Alarm upper limit |
| DM 1004 | 0080 | Deadband for alarm |

## Programming

The types of programming required to use an Analog Output Unit are described in this section. Refer to the operation manual for the $\mathrm{C} 200 \mathrm{H} / \mathrm{C} 200 \mathrm{HS}$ for details on programming.

## Writing Output Data

## Limiting Outputs

Monitoring Outputs

Output data can be written using instructions like MOV(21) and OUT. The following instruction move the binary contents of DM 0000 and DM 0001 to IR 100 and IR 101, causing the data to be converted to analog signals and to be sent to outputs 1 and 2.


This example assumes that the data settings given at the beginning of this section have already been made.
The output will be limited to between 1.25 and 4.75 V when the following instructions are executed.


This example assumes that the data settings given at the beginning of this section have already been made.
Upper and lower limit alarms will be output as described below when the following instructions are executed.
Upper limit alarm: ON when output reaches 19 mA until it drops to 18.5 mA Lower limit alarm: ON when output falls below 6 mA until it reaches 6.5 mA


The alarm outputs can be wire externally using external terminals A8 and B8. The ALARM indicator on the Unit will light when any Alarm Flag is ON.

## Pulse Output

This example shows how to set pulse outputs on output 1. The pulse output settings are given in the following table.

| Item |  | Value | Data setting |
| :--- | :--- | :--- | :--- |
| Pulse output | Duty | $80 \%$ | OCCC in IR 100 |
|  | Pulse period | 2 s | Turn ON IR 10200 |



Turn OFF pin 2 (specifying output 1) and turn ON pin 3 (enabling pulse output) on the back-panel DIP switch before starting.
Execute the following instructions in the program. Pulse outputs will be made on output 1.


## 3-4 Troubleshooting

## Detection When Errors <br> Occur

When an error occurs, the contents are output to the SR and HR areas. The following tables show the various errors that may occur, along with their probable causes and remedies.

| Unit error | Probable causes and operations | Possible remedies |
| :--- | :--- | :--- |
| Setting error | The data set in the DM area is wrong. In this case, <br> the Setting Error Flag (IR $\mathrm{n}+3$, bit 00) will be ON. | Check the contents of the data. |
| RUN indicator not lit | The RUN indicator on the Unit is not lit even though <br> power is turned on to the PC, and none of the errors <br> described in this table are applicable. | Replace the Unit. |


| CPU error | Probable causes and operations | Possible remedies |
| :---: | :---: | :---: |
| CPU waiting | - The Special I/O Unit is defective. <br> - The PC will not run. | - Replace the Special I/O Unit. <br> - The defective Unit should appear as \$ signs only in the I/O table read operation. |
| Duplicated unit number | The same number is assigned to more than one Special I/O Unit. In this case the PC will not run and SR25415 will turn ON. | Do not assign the same number to more than one Unit. Use the I/O table read operation to display unit numbers. |
| Special I/O Unit error | An error has occurred in the refresh signal between the CPU and the Special I/O Unit. In this case, only the Special I/O Unit stops. SR 25415 is turned ON. | Check AR 0000 to AR 0009 for the unit number of the Unit in error. After correcting the error, turn ON the proper bit in AR 0100 to AR 0109. If the error does not clear after initialization, replace the Unit. |

Special I/O Unit Error Detection Bit (SR)

| Bit | Error | Explanation | Operation status |
| :---: | :--- | :--- | :--- |
| 25415 | Duplicated unit number | One number is assigned to more <br> than one Special I/O Unit. | PC operation stops. |
|  | Special I/O Unit error | An error has occurred in the refresh <br> signal between the CPU and the <br> Special I/O Unit | Operation stops only for the faulty <br> Unit. |

## Special I/O Unit Error Flags (AR)

| Bit | Item | Function |
| :---: | :---: | :---: |
| AR 0000 | Unit \#0 Error Flag | When one of the CPU errors described above occurs, the AR bit turns ON for the Unit where the error occurred. |
| AR 0001 | Unit \#1 Error Flag |  |
| AR 0002 | Unit \#2 Error Flag |  |
| AR 0003 | Unit \#3 Error Flag |  |
| AR 0004 | Unit \#4 Error Flag |  |
| AR 0005 | Unit \#5 Error Flag |  |
| AR 0006 | Unit \#6 Error Flag |  |
| AR 0007 | Unit \#7 Error Flag |  |
| AR 0008 | Unit \#8 Error Flag |  |
| AR 0009 | Unit \#9 Error Flag |  |

## Special I/O Unit Restart Bits (AR)

Turn ON the Special I/O Unit Restart Bits in the following circumstances:

- After DM data has been set or replaced.
- To restart Unit operation after clearing an error.

The same effect can be achieved by turning off the power to the PC and then turning it on again.

| Bit | Item | Function |
| :---: | :---: | :---: |
| AR 0100 | Unit \#0 Restart Bit | Special I/O Units can be restarted by turning the corresponding bits ON . |
| AR 0101 | Unit \#1 Restart Bit |  |
| AR 0102 | Unit \#2 Restart Bit |  |
| AR 0103 | Unit \#3 Restart Bit |  |
| AR 0104 | Unit \#4 Restart Bit |  |
| AR 0105 | Unit \#5 Restart Bit |  |
| AR 0106 | Unit \#6 Restart Bit |  |
| AR 0107 | Unit \#7 Restart Bit |  |
| AR 0108 | Unit \#8 Restart Bit |  |
| AR 0109 | Unit \#9 Restart Bit |  |

# Appendix A <br> Standard Models 

## Analog Output Unit

| PC | Model |
| :--- | :--- |
| C200H/C200HS | C200H-DA001 |

## Analog Input Unit

| PC | Model |
| :--- | :--- |
| $\mathrm{C} 200 \mathrm{H} / \mathrm{C} 200 \mathrm{HS}$ | $\mathrm{C} 200 \mathrm{H}-\mathrm{AD} 001$ |

## Appendix B <br> Specifications

## C200H-AD001 Analog Input Unit

## General Specifications

All general specifications of the C200H-AD001 Analog Input Unit conform to those of the C Series.

## Performance Specifications

| Item | Specifications |  |
| :---: | :---: | :---: |
| Number of analog inputs | 4 max. |  |
| Input signal range (note 1) | Voltage input | 1 to 5 V |
|  |  | 0 to 10 V |
|  | Current input | 4 to 20 mA |
| Max. input signal (note 2) | Voltage input | $\pm 15 \mathrm{~V}$ |
|  | Current input | $\pm 30 \mathrm{~mA}$ |
| Input impedance | Voltage input | $1 \mathrm{M} \Omega \mathrm{min}$. |
|  | Current input | $250 \Omega$ (rated value) |
| Resolution | 1/4000 max. (full scale) |  |
| Converted data | 12-bit binary (0000 to 0FA0) |  |
| Accuracy (note 3) | $25^{\circ} \mathrm{C}$ | $\pm 0.5 \%$ (full scale, including linearity error) |
|  | $0^{\circ}$ to $55^{\circ} \mathrm{C}$ | $\pm 1.0 \%$ (full scale, including linearity error) |
| Conversion time (note 4) | 2.5 ms max./point |  |
| Isolation | Between input terminals and PC: photocoupler |  |
|  | Between input terminals: none |  |
| External connections | 19-pin terminal block (removable) |  |
| Power consumption | 550 mA max. at 5 VDC |  |
| Dimensions | $34.5 \times 130 \times 128(\mathrm{~W} \times \mathrm{H} \times \mathrm{D}) \mathrm{mm}$ (see last page of this appendix) |  |
| Weight | 450 g max. |  |

Note 1. All points on the same Unit must use the same input range except for the 1 to $5-\mathrm{V}$ and 4 to $20-\mathrm{mA}$ ranges, which can be specified by point.
2. Operation in ranges beyond the maximum input signals will damage the Unit. Operate within the ranges listed above.
3. The accuracy is given for full scale $(4,000)$. For example, an accuracy of $\pm 5 \%$ means a maximum error of 20 (BCD).
4. This is the time it takes for a full range input signal to be converted and to be stored in the memory of the Unit. It takes at least one scan before the converted data is read by the CPU.

## Input Specifications

Converted output data
(Top: Binary
Parentheses: BCD)


Note 1. All points on the same Unit must use the same input range except for the 1 to $5-\mathrm{V}$ and 4 to $20-\mathrm{mA}$ ranges, which can be specified by point. Refer to e-1-2 Switch Settings for setting methods.
2. The maximum or minimum output value will be maintained if the input signals goes beyond the maximum ( $10 \mathrm{~V}, 5 \mathrm{~V}$, or 20 mA ) or minimum ( $0 \mathrm{~V}, 1 \mathrm{~V}$, or 4 mA ).

## C200H-DA001 Analog Output Unit

All general specifications of the C200H-DA001 Analog Output Unit conform to those of the C Series.

| Item | Specifications |  |
| :---: | :---: | :---: |
| Number of analog outputs | 2 |  |
| Output signal range (note 1) | Voltage outputs | 1 to 5 V |
|  |  | 0 to 10 V |
|  | Current outputs | 4 to 20 mA |
| Max. output impedance | Voltage output: $0.5 \Omega$ |  |
| Max. output current | Voltage output: 15 mA |  |
| Max. load resistance | Current output: $400 \Omega$ |  |
| Resolution | 1/4095 max. (full scale) |  |
| Set data | 12-bit binary (0000 to 0FFF) |  |
| Accuracy (note 2) | $25^{\circ} \mathrm{C}$ | $\pm 0.5 \%$ max. (full scale, including linearity error) |
|  | $0^{\circ}$ to $55^{\circ} \mathrm{C}$ | $\pm 1.0 \%$ max. (full scale, including linearity error) |
| Conversion time (note 3) | 2.5 ms max./point |  |
| Isolation | Between output terminals and PC: photocoupler |  |
|  | Between output terminals: none |  |
| External connections | 19-pin terminal block (removable) |  |
| Power consumption | 650 mA max. at 5 VDC |  |
| Dimensions | $34.5 \times 130 \times 128(\mathrm{~W} \times \mathrm{H} \times \mathrm{D}) \mathrm{mm}$ (see last page of this appendix) |  |
| Weight | 450 g max. |  |

Note 1. All points on the same Unit must use the same output range except for the 1 to $5-\mathrm{V}$ and 4 to $20-\mathrm{mA}$ ranges, which can be specified by point.
2. The accuracy is given for full scale $(4,095)$. For example, an accuracy of $\pm 5 \%$ means a maximum error of 20 (BCD).
3. This is the time from after the data has been written to the Unit until an analog output appears. The output data will not be correct if output data is rewritten faster than it can be output.

## Output Specifications



Note All points on the same Unit must use the same output range except for the 1 to $5-\mathrm{V}$ and 4 to $20-\mathrm{mA}$ ranges, which can be specified by point. Refer to $\mathcal{S}^{-1-2}$ Switch Settings for setting methods.

## Dimensions (Unit: mm)

The dimensions are the same for both the C200H-AD001 and C200H-DA001.


# Appendix C <br> Data Memory Coding Sheets 

## C200H-AD001 Analog Input Unit

| C200H-AD001 |  | Unit number:_Dsage |  |  |  |
| :---: | :--- | :--- | :--- | :--- | :--- |
| DM address <br> (rightmost <br> digits) | Data |  |  |  |  |
| 00 |  |  |  |  | Scaling lower limit for input 1 |
| 01 |  |  |  |  | Scaling upper limit for input 1 |
| 02 |  |  |  |  | Scaling lower limit for input 2 |
| 03 |  |  |  |  | Scaling upper limit for input 2 |
| 04 |  |  |  |  | Scaling lower limit for input 3 |
| 05 |  |  |  |  | Scaling upper limit for input 3 |
| 06 |  |  |  |  | Scaling lower limit for input 3 |
| 07 |  |  |  |  | Scaling upper limit for input 4 |
| 08 |  |  |  |  | Number of terms for mean value for input 1 |
| 09 |  |  |  |  | Number of terms for mean value for input 2 |
| 10 |  |  |  |  | Number of terms for mean value for input 3 |
| 11 |  |  |  |  | Number of terms for mean value for input 4 |

## C200H-DA001 Analog Output Unit

| C200H-DA001 |  | Unit number:__ Usage |  |  |
| :---: | :--- | :--- | :--- | :--- |
| DM address <br> (rightmost <br> digits) | Data to DM1_04 |  |  |  |
| 00 |  |  |  |  |
| 01 |  |  |  |  |
| 02 |  |  |  | Uperer output limit |
| 03 |  |  |  |  |
| 04 |  |  |  |  |

## Index

## A

A/D conversion data,
analog input vs. digital output,

## B-C

block diagram
C200H-AD001,
C200H-DA001,
configurations, system, considerations,

## D-F

data memory coding sheet,
data reading mode, setting,
digital output vs. analog input,
dimensions, $\square$
disconnection detection,
DM area allocation
C200H-AD001, C200H-DA001,

DM area contents, C200H-AD001
field devices,
I
indicators
C200H-AD001, C200H-DA001,
input disconnection detection function,
input signal range, setting,
inputs
number, setting, signal range, setting, $\square \square$
IR area allocation
C200H-AD001, C200H-DA001,

IR area contents
C200H-AD001,
C200H-DA001,

## M-N

mean function,
models,
number of inputs, setting,
$\square$
output limit alarm function,
output limit function,
output signal range, setting,,
outputs, signal range, setting, $\square \square$

## P

peak value function,
precautions,,$\square$
applications, $\square$
general,
operating environment,
safety,
programming examples
C200H-AD001,
C200H-DA001
pulse output function,
pulse output line, setting,
pulse outputs, setting,
S
scaling function,
Slave Racks,
specifications,
square root function,
switches
C200H-AD001,
C200H-DA001,
T-W
troubleshooting
C200H-AD001, C200H-DA001,
unit number, setting, Analog Input Unit,
unit numbers, setting
C200H-AD001,
C200H-DA001, $\qquad$
Units, number,
wiring
C200H-AD001, C200H-DA001,

## Revision History

A manual revision code appears as a suffix to the catalog number on the front cover of the manual.
Cat. No. W127-E1-4

Revision code

The following table outlines the changes made to the manual during each revision. Page numbers refer to the previous version.

| Revision code | Date | Revised content |
| :---: | :---: | :--- |
| 3 | June 1990 | Correction of notation and format. Resource document 29-121D. |
| 3A | November 1993 | Page 16: In the Block Diagram, all "inputs" have been corrected to "outputs." <br> Page 25: The last line of the second paragraph has been corrected. |
| 3B | May 1995 | Address change |
| 3C | September 1995 | The manual was restructured, expanded, and mostly rewritten. |
| 4 | February 2001 | The insert providing precautionary information was moved to page 35. A Precau- <br> tions section was added. In addition, the following changes were made. <br> Pages 4, 5, 15, 18, 24, 36: Changes made to model numbers. <br> Pages 12, 13: Note added. |


[^0]:    !WARNING Failure to read and understand the information provided in this manual may result in personal injury or death, damage to the product, or product failure. Please read each section in its entirety and be sure you understand the information provided in the section and related sections before attempting any of the procedures or operations given.

