MITSUBISHI Temperature Control Module

MITSUBISHI General-Purpose PROGRAMMABLE CONTROLLER

User's Manual (Hardware)

Q64TCRT Q64TCRTBW

Thank you for purchasing the Mitsubishi general-purpose programmable controller MELSEC-Q series.

Prior to use, please read this manual thoroughly and familiarize yourself with the product



Mitsubishi Programmable Controller

MODEL	Q64TCRT-U-H-JE
MODEL CODE	13JQ98

IB(NA)-0800121-B(0709)MEE

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SAFETY PRECAUTIONS •

(Read these precautions before using.)

When using Mitsubishi equipment, thoroughly read this manual and the associated manuals introduced in this manual. Also pay careful attention to safety and handle the module properly.

These SAFETY PRECAUTIONS classify the safety precautions into two categories: "DANGER" and "CAUTION".

Procedures which may lead to a dangerous condition and cause death or serious injury, if not carried out properly.
Procedures which may lead to a dangerous condition and cause superficial to medium injury, or physical damage only, if not carried out properly.

Depending on circumstances, procedures indicated by <u>P</u>CAUTION may also be linked to serious results.

In any case, it is important to follow the directions for usage.

Store this manual in a safe place so that you can take it out and read it whenever necessary. Always forward it to the end user.

[DESIGN PRECAUTIONS]

Do not write data to the "read-only area" in the buffer memory of the intelligent function module.

Do not turn on/off the "reserved" signals among the I/O signals to/from the programmable controller CPU.

Doing so can malfunction the programmable controller system.

Depending on the malfunction of the external output transistor, there may be cases where the output is ON or OFF status. Install external monitoring circuitry for output signals that may lead to major accidents.

Do not bunch the control wires or communication cables with the main circuit or power wires, or install them close to each other. They should be installed 100 mm(3.94 inch) or more from each other.

Not doing so could result in noise that may cause malfunction.

[INSTALLATION PRECAUTIONS]



[WIRING PRECAUTIONS]

 CAUTION
Be careful not to let foreign matters such as sawdust or wire chips get inside the module. They may cause fires, failure or malfunction.
The top surface of the module is covered with protective film to prevent foreign objects such as cable offcuts from entering the module when wiring. Do not remove this film until the wiring is complete. Before operating the system, be sure to remove the film to provide adequate heat ventilation.
Be sure to fix communication cables or power supply cables leading from the module by placing them in the duct or clamping them. Cables not placed in the duct or without clamping may hang or shift, allowing them to be accidentally pulled, which may cause a module malfunction and cable damage.

[WIRING PRECAUTIONS]

Do not grab on the cable when removing the communication or power
cable connected to the module.
When disconnecting a cable without a connector, first loosen the screws on
the part that is connected to the module.
Pulling the cable when it is still connected to the module may cause
damage to the module or cable, or misoperation due to cable contact
failure.
Always ground the shielded cable for the programmable controller.
There is a risk of electric shock or malfunction.
When wiring, be sure to verify the rated voltage of the product as well as
the terminal layout. Fire or failure may result if incorrect voltage is input or
incorrect wiring is performed.
Connecting terminals with incorrect voltage may result in malfunction or
mechanical failure.

[STARTUP AND MAINTENCE PRECAUTIONS]

 Mounting/removing the module to/from the base and the terminal block is limited to 50 times after using a product. (IEC 61131-2-compliant) Failure to do so may cause malfunctions.

Print Date	* Manual Number	Revision
Jun.,2000	IB (NA)-0800121-A	First edition
Sep.,2007	IB (NA)-0800121-B	Partial correction
		SAFETY PRECAUTIONS, CONTENTS, Conformance to the EMC Directive/Low Voltage Directive Section 2.1, 2.2, 3.1, 5.1, 5.2, Chapter, 4, 6

* The manual number is given on the bottom right of the top cover.

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About the Manuals

The following manuals are related to this product. Referring to this list, please request the necessary manuals.

Detailed manual	
Manual Name	Manual Number (Model Code)
Q64TCTT, Q64TCTTBW, Q64TCRT, Q64TCRTBW	SH-080108
type Temperature Control Module User's Manual	(13JT11)

Conformance to the EMC Directive/Low Voltage Directive

When Mitsubishi programmable controller conforming to the EMC Directive/Low Voltage Directive is mounted into your product and the product is made to conform to the EMC Directive/Low Voltage Directive, refer to the user's manual of the module.

The EMC Directive/Low Voltage Directive-conforming model of the programmable controller has a CE logo on its rating plate.

1. OVERVIEW

This user's manual provides the specifications, handling, part names and others of the following temperature control modules used with the MELSEC-Q series CPU modules.

- Q64TCRT temperature control module
- Q64TCRTBW temperature control module with wire break detection feature

2. SPECIFICATIONS

The specifications of the Q64TCRT(BW) are indicated below.

2.1 Performance Specifications

Item		Specifications	
		Q64TCRT	Q64TCRTBW
Control output		Transistor output	
Number of ter	nperature input points	4 channel	s/module
Usable platinu	im temperature-	Pofor to S	action 2.2
measuring res	sistors	Relef to Section 2.2	
	Ambient	Full-scale \times (±0.3%)	
	temperature:		
Accuracy	25°C ±5°C		
Accuracy	Ambient		
	temperature:	Full-scale	× (±0.7%)
	0°C to 55°C		
Sampling peri	od	0.5s/4 channels	
	00	(constant independently of the number of channels used)	
Control output	t period	1 to 100s	
Input impedar	nce	1M	Ω
Input filter		0 to 100s (0: Input filter OFF)	
Sensor compe	ensation value setting	-50.00 to 50.00%	
Operation at s	sensor input		
disconnection			
Temperature	control system	PID ON/OFF pulse of	or 2-position control
	PID constant setting	Setting can be ma	de by auto tuning
PID constant range	Proportional band (P)	0.0 to 1000.0% (0:	2-position control)
	Integral time (I)	1 to 3600s	
	Derivative time (D)	0 to 3600s (Set 0 for PI control.)	
Set value setting range		Within temperature range	set to the used platinum
		temperature-measuring resistor	
Dead band setting range		0.1 to 10.0%	

Item		Specifications			
		Q64TCRT	Q64TCRTBW		
	Output signal	ON/OFF pulse			
	Rated load voltage	10 to 3	10 to 30VDC		
	Max. load current	0.1A/point	0.1A/point 0.4A/common		
Transistor	Max. inrush current	0.4A 10ms			
output	Leakage current at OFF	0.1mA or less			
	Max. voltage drop at ON	1.0VDC (TYP) 0.1A	2.5VDC (MAX) 0.1A		
	Response time	OFF→ON: 2ms or less	$ON \rightarrow OFF$: 2ms or less		
Insulation meth	nod	Between input and grounding Between input and channel	: Transformer insulation : Transformer insulation		
Dielectric withs	tand voltage	Between input and grounding	: 500VAC for 1 minute		
Dielectric withe		Between input and channel	: 500VAC for 1 minute		
Insulation resis	stance	Between input and grounding	: 500VDC 20M Ω or more		
		Between input and channel	: 500VDC 20M Ω or more		
Heater disconnection detection	Current sensor*1		The following current sensor made by URD Co., Ltd. Input accuracy • CTL-12-S36-8(0.0 to 100.0A) • CTL-6-P-H(0.00 to 20.00A)		
specifications	Input accuracy	T	Full scale × (±1.0%)		
	Number of alert delays	* 	3 to 255		
I/O occupied points *2		16 points/slot (I/O assignment: 16 intelligent points)	32 points/2 slots (Default I/O assignment: 16 free points + 16 intelligent points)		
Connection terminals		18-point terminal block	Two 18-point terminal blocks		
Applicable wire size (mm ²)		0.3 to 0.75			
Applicable crimping terminals		R1.25-3,1.25-YS3,RAV1.25-3,V1.25-YS3A			
Internal current	t consumption (A)	0.55	0.64		
Weight (kg)		0.20	0.30		
Outline dimensions (mm)		27.4 (W) × 98 (H) × 112 (D)	55.2 (W) × 98 (H) × 112 (D)		

*1 : Only the current sensor of URD Co., Ltd. may be used.

*2 : When using the Q64TCRTBW, the device numbers of the I/O signals are incremented by 16 points due to the empty points of the left-hand side slot. In this manual, therefore, read the I/O signals as indicated below depending on the module used.

Example) When the signal is indicated as Yn1

When using Q64TCRT: Y1 When using Q64TCRTBW: Y11 *3 : For the noise immunity, withstand voltage, insulation resistance and others in the programmable controller system using this module, refer to the power supply module specifications given in the used CPU module user's manual.

2.2 Types, Measured Temperature Ranges and Data Resolutions of Usable Platinum Temperature Measuring Resistors

Platinum	°C		°Ę	
temperature measuring resistor type	Measured temperature range	Data resolution	Measured temperature range	Data resolution
Dt100	-200.0 to 600.0	0.1	-300 to 1100	1
FIIOU	-200.0 to 200.0	0.1	-300.0 to 300.0	0.1
JPt100	-200.0 to 500.0	0.1	-300 to 900	1
	-200.0 to 200.0	0.1	-300.0 to 300.0	0.1

3. LOADING AND INSTALLATION

3.1 Handling Instructions

There are the following instructions for handling the Q64TCRT(BW).

- (1) Do not drop the case and connectors of the module and subject them to hard impact.
- (2) Tighten the fixing and terminal screws of the module within the following ranges.

Screw Location	Tightening Torque Range
Module fixing screw (M3 screw)	36 to 48N⋅cm
Terminal block terminal screw (M3 screw)	42 to 58N⋅cm
Terminal block fixing screw (M3.5 screw)	66 to 89N⋅cm

3.2 Installation Environment

Refer to the user's manual of the CPU module used.

4. NAMES AND SETTINGS OF THE PARTS



1)	RUN LED	Off : 5V power switched off, a watchdog timer error occurred, in the module changeable status during online module change, or a CPU stop error occurred when the intelligent function module switches of all channels are set to "CLEAR".
		Indicates the error status of the Q64TCRT(BW).
2)	ERR. LED	Elicker : Write data error occurrence
		Ω
		Indicates the alarm status of the O64TCRT(BW)
		Ω n · Alarm occurrence
		Flicker : Process value (PV) is outside the measured
3)		temperature range
3)		Loop wire break was detected
		Sensor is not connected
		Off : No alarm occurrence
		Indicates the heater wire break detection status of the
4)	HBA LED	Q04TCRTDW. On Heater wire break was detected
		Off : Heater wire break is not detected
		Used for temperature senser input transister output and
5)	Terminal block*	ourrent concer (CT) input

* : The terminal block layout depends on the module used. The respective terminal block layouts are shown on the next page.

(1) When using Q64TCRT

Terminal Number	Signal Name
1	L1
2	L2
3	L3
4	L4
5	COM-
6	Reserved
7	A1
8	A2
9	B1
10	B2
11	b1
12	b2
13	A3
14	A4
15	B3
16	B4
17	b3
18	b4

(2) When using Q64TCRTBW

Terminal Number	Signal Name	
1	Reserved	L1
2	CT1+	L2
3	CT1-	L3
4	CT2+	L4
5	CT2-	COM-
6	CT3+	Reserved
7	CT3-	A1
8	CT4+	A2
9	CT4-	B1
10	CT5+	B2
11	CT5-	b1
12	CT6+	b2
13	CT6-	A3
14	CT7+	A4
15	CT7-	B3
16	CT8+	B4
17	CT8-	b3
18	Reserved	b4

5. WIRING

5.1 Wiring Instructions

- (1) Use separate cables for the AC control circuit and Q64TCRT(BW)'s external input signals to avoid the influence of AC side surges and inductions.
- (2) Do not run the module cables near, or bundle them with, the main circuit and high-voltage cables and the load cables from other than the programmable controller.

Always place the temperature sensors more than 100mm (3.94inch) away from the main circuit cables and AC control circuit. Fully keep the sensors away from high-voltage cables and circuits which include high frequencies, e.g. inverter's main load circuit.

Not doing so can make the sensors more susceptible to noises, surges and inductions.

(3) Earth the shielded wire or shielded cable to FG of the programmable controller.

However, depending on the external noise conditions, external earthing may be recommended.

5.2 External Wiring (1) When using Q64TCRT



*1 : Always use shielded wires for cables.

(2) When using Q64TCRTBW



*1: Always use shielded wires for cables.

POINT

When using the heater wire break detection feature, you need to make CT input channel assignment setting.

In the above wiring example, as CT1 is used with the loop of channel 1, set 1 (channel 1) to the channel assignment setting buffer memory (108H) of CT1.

The Q64TCRT(BW) allows you to set the output status at an error stop of the programmable controller CPU by making the intelligent function module switch setting.

Make the intelligent function module switch setting using the I/O assignment setting of GX Developer.

You can make setting easily by entering hexadecimal numbers into 4 digits.

	Setting Item		
Switch 1	CH4 CH3 CH2 CH1 H	Output setting at CPU stop error 0 : CLEAR Other than 0 : HOLD	
Switch 2	Empty		
Switch 3	Empty		
Switch 4	Empty		
Switch 5	Empty		



Unit: mm (inch)

Warranty

Mitsubishi will not be held liable for damage caused by factors found not to be the cause of Mitsubishi; machine damage or lost profits caused by faults in the Mitsubishi products; damage, secondary damage, accident compensation caused by special factors unpredictable by Mitsubishi; damages to products other than Mitsubishi products; and to other duties.

For safe use

- This product has been manufactured as a general-purpose part for general industries, and has not been designed or manufactured to be incorporated in a device or system used in purposes related to human life.
- Before using the product for special purposes such as nuclear power, electric power, aerospace, medicine or passenger movement vehicles, consult with Mitsubishi.
- This product has been manufactured under strict quality control. However, when installing the product where major accidents or losses could occur if the product fails, install appropriate backup or failsafe functions in the system.

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